

Table of Contents

PREFACE.....	IX
ACKNOWLEDGEMENTS	XIII
CHAPTER 1 THE 8051 ARCHITECTURE.....	1
1.1 THE 8051 MICROCONTROLLER	1
1.2 THE CENTRAL PROCESSING UNIT	1
1.3 THE PROGRAMMER'S VIEW OF THE 8051 MEMORY SPACES.....	2
1.3.1 The Harvard Architecture	2
1.3.2 Register Space	4
1.3.3 Bit-Addressable Memory	6
1.4 ACCESSING THE PERIPHERALS AND THE SPECIAL FUNCTION REGISTERS.....	7
1.5 INTERFACING TO THE INPUT / OUTPUT PORTS.....	9
1.5.1 Electrical Characteristics of I/O Ports.....	10
1.5.2 Driving Light Loads	11
1.5.3 Reading Inputs	12
CHAPTER 2 THE MCS-51 ASSEMBLY LANGUAGE.....	15
2.1 ADDRESSING MODES.....	15
2.2 MCS-51 INSTRUCTIONS	17
2.3 DATA TRANSFER INSTRUCTIONS	20
2.4 DATA PROCESSING INSTRUCTIONS.....	22
2.5 PROGRAM FLOW CONTROL INSTRUCTIONS.....	24
2.5.1 Interrupt Service Routines	24
2.6 SIMPLE ASSEMBLY LANGUAGE EXERCISES	26
2.7 ABSOLUTE ASSEMBLY VERSUS RELATIVE ASSEMBLY.....	28
CHAPTER 3 SIMPLE SERIAL INPUT / OUTPUT	33
3.1 INITIALIZING THE 8051 SERIAL PORT	33
3.2 TRANSMITTING CHARACTERS IN ASSEMBLY LANGUAGE.....	34
3.3 TRANSMITTING STRINGS IN ASSEMBLY LANGUAGE.....	35
3.4 TRANSMITTING CHARACTERS AND STRINGS IN C	36
3.5 TRANSMITTING NUMBERS	38
3.5.1 Binary-to-ASCII Conversion Routines in Assembly Language	40
3.5.2 Binary-to-ASCII Conversion Routines in C	45
CHAPTER 4 INPUT / OUTPUT PORTS	49
4.1 A SIMPLE I/O PROGRAM IN ASSEMBLY	49
4.2 A SIMPLE I/O PROGRAM IN C.....	50
4.3 DRIVING HIGH-CURRENT LOADS	52

4.4 USING BIPOLAR SWITCHING TRANSISTORS	54
4.5 USING MOSFET SWITCHING TRANSISTORS	56
4.6 USING TRANSISTOR ARRAYS.....	59
4.7 DRIVING STEPPER MOTORS	61
4.8 OPTICALLY ISOLATED INPUTS AND OUTPUTS.....	66
4.9 USING INTERRUPTS.....	68
CHAPTER 5 TIMERS AND COUNTERS	73
5.1 CONFIGURING THE TIMERS.....	73
5.2 COUNTING EXTERNAL PULSES.....	75
5.3 SOFTWARE TIMERS	77
5.4 MEASURING PULSE LENGTHS.....	79
5.5 TIMER 2 OF THE 8052	81
5.6 THE PROGRAMMABLE TIMER/COUNTER ARRAY (PTRA) UNIT OF THE 80C535.....	83
5.6.1 Pulse-Width Modulation with the 80C535 PTRA Unit.....	85
5.7 PULSE WIDTH MODULATION WITH THE 8051 TIMER 0.....	89
CHAPTER 6 ANALOG INPUTS AND OUTPUTS	95
6.1 ANALOG-TO-DIGITAL CONVERSION UNIT OF THE 80C535	95
6.2 ANALOG-TO-DIGITAL CONVERSION USING AN EXTERNAL 555 TIMER.....	98
6.2.1 Measuring the External 555 Timer Pulse Period	101
6.2.2 Counting the External 555 Timer Pulses	105
6.3 ANALOG-TO-DIGITAL CONVERSION USING AN EXTERNAL SERIAL ADC UNIT.....	107
6.4 DIGITAL-TO-ANALOG CONVERSION	114
6.5 DIGITAL-TO-ANALOG CONVERSION USING AN EXTERNAL SERIAL DAC UNIT.....	115
6.6 SIGNAL PROCESSING BY COMBINING ANALOG-TO-DIGITAL AND DIGITAL-TO-ANALOG CONVERSION.....	120
6.7 FEEDBACK CONTROL BY COMBINING ANALOG-TO-DIGITAL CONVERSION AND PULSE-WIDTH MODULATION.....	121
CHAPTER 7 PROGRAMMING A ROVING ROBOT	125
7.1 THE HARDWARE PLATFORM	125
7.2 LOW-LEVEL ROUTINES.....	128
7.2.1 Bumper Switch Routines.....	128
7.2.2 Buzzer Routines	129
7.2.3 Motor Driver Routines	130
7.2.4 Other Low-Level Routines.....	132
7.3 HIGH-LEVEL ROUTINES	132
7.3.1 Open-Loop Control.....	132
7.3.2 Using the Bumper Switch Information.....	135
7.3.3 Using the Light-Dependent Resistors	136
7.3.4 Performing Auxiliary Tasks in the Background	137
7.4 A STATE-SPACE APPROACH	138

7.5 LEARNING	142	
7.6 EXTENSIONS	143	
APPENDIX A READS51 SOFTWARE	145	
APPENDIX B A BRIEF REVIEW OF THE C PROGRAMMING LANGUAGE.....		147
B.1 C LANGUAGE PHILOSOPHY.....	147	
B.1.1 Ingredients of a C Program	148	
B.1.2 Code Appearance and Style	148	
B.2 FUNCTIONS.....	149	
B.3 VARIABLES	149	
B.3.1 Scalars	149	
B.3.2 Pointers	150	
B.3.3 Arrays	151	
B.4 CONSTANTS	151	
B.4.1 Compiler Directives	151	
B.5 STATEMENTS.....	152	
B.5.1 Compound Statements	152	
B.5.2 Expressions.....	152	
B.5.3 Conditions	154	
B.5.4 Iteration Statements	154	
B.5.5 Selection Statements	157	
B.6 COMMENTS.....	159	
B.7 STANDARD (RUN TIME) LIBRARIES.....	160	
B.8 REFERENCES.....	160	
APPENDIX C NUMBER SYSTEMS	161	
C.1 BINARY NUMBERS.....	161	
C.2 HEXADECIMAL NUMBERS.....	162	
C.3 BINARY-CODED DECIMAL NUMBERS	163	
APPENDIX D 8051 TOOLS AND INFORMATION SOURCES.....	165	
D.1 JOURNALS AND MAGAZINES	165	
D.2 BOOKS	167	
D.3 CHIP MANUFACTURERS.....	169	
D.4 SOFTWARE VENDORS	171	
D.5 HARDWARE VENDORS	176	
D.5.1 Single-Board Computers.....	176	
D.5.2 Parts Suppliers.....	178	